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OSLC for Cognitive Cross-Checking of System Models



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- US-funded(DoD), UK-funded(MoD) and EU-funded projects
 - US research project in collaboration with the AFRL.
 - UK research projects in collaboration with BAE Systems, Atlas Elektonik, and seabyte.
 - EU research projects in collaboration with Airbus, Eurocopter, Goodrich, Autoflug, ÁSG, and Secondo Mona.
- Autonomy-based projects
 - Autonomously cross-checked models from multidisciplinary design teams of highintegrity systems.
 - Autonomous decision-making support for avionics analytics.
 - Remote integration of capabilities from autonomous ground vehicles for defence.
 - Automation of distributed aircraft fuel management systems tested in lab and realscale rigs.
 - Intelligent control architecture for autonomous maritime vehicles.
 - Autonomous reconfiguration of production lines.
- Over 100 publications, including a book and 5 book chapters.



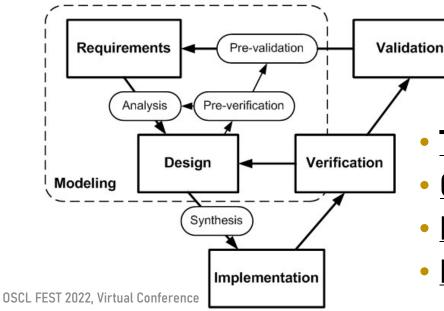


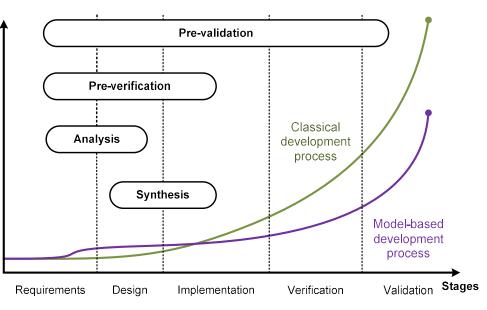
- Introduction
- Background
- Example
- Approach
- Reflection



Early Efforts to Reduce Costs and Risk

- Focus: Dependable Cyber-Physical Systems #
- <u>Feature:</u> High-integrity; safety, security, etc. 🐐
- <u>Challenge</u>: SDLC risks & costs increasing
- <u>Trend:</u> Pre-verification & pre-validation

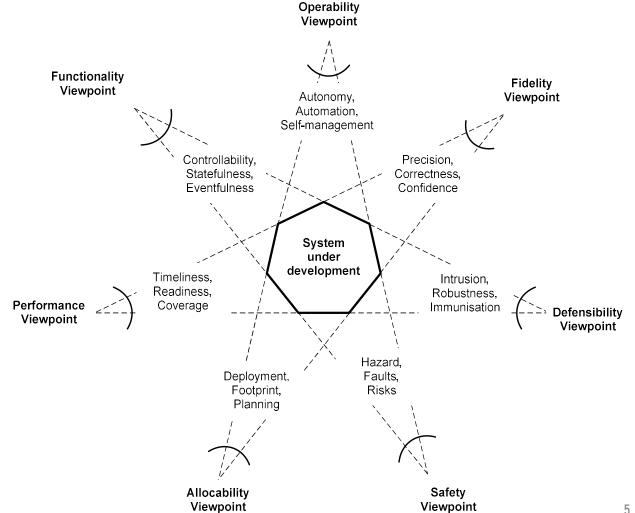




- **<u>Target:</u>** Functional & non-functional requirements
- Constrain: Multiple models and teams
- <u>Need:</u> Agile model cross-checking
- Problem: Deadlocks between development Teams

Different Views/Models of the Same System

- One single (unified) system model is impossible
- But it could be a notationunified system model
- The approach is to merge notation from different domain-specific representations
- To check the impact of each representation on others can quickly be reflected.





Related Existing Technologies

- Integration of Models
 - Cyber-Physical Modelling [1]
 - OSLC
 - MIC (Model-Integrated Computing) [2]
 - CIF (Compositional Interchange Format) [3]
- Multi-View Tools
 - Modelica (control) [4], 20sim (mechatronics) [5]
 - MIC, MVM [6]
- Single-View Tools
 - AADL [7], MARTE [8]
 - SysML, UML
 - COMPASS [9], CRYSTAL [10]
 - ISO/IEC/IEEE 42010 standard [11]

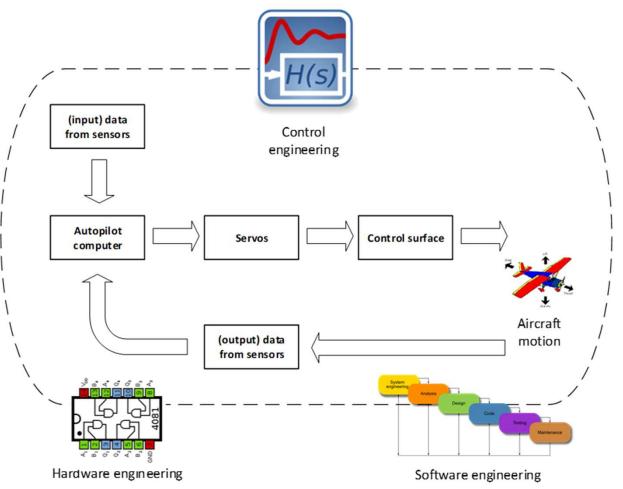




- An automatic Flight Control System (AFCS).
- Three distinct models (views) from different engineering disciplines are considered to design the above AFCS:
 - a control engineering model,
 - a software application model
 - a hardware platform model.
- They have different description languages to model the AFCS, e.g. block diagrams, UML diagrams, and AADL diagrams.
- Three application scenarios:
 - a software application model connected to a hardware platform model and a control engineering model.
 - a hardware platform model connected to a software application model and a control engineering model.
 - A control engineering model connected to a hardware platform model and a software application model.

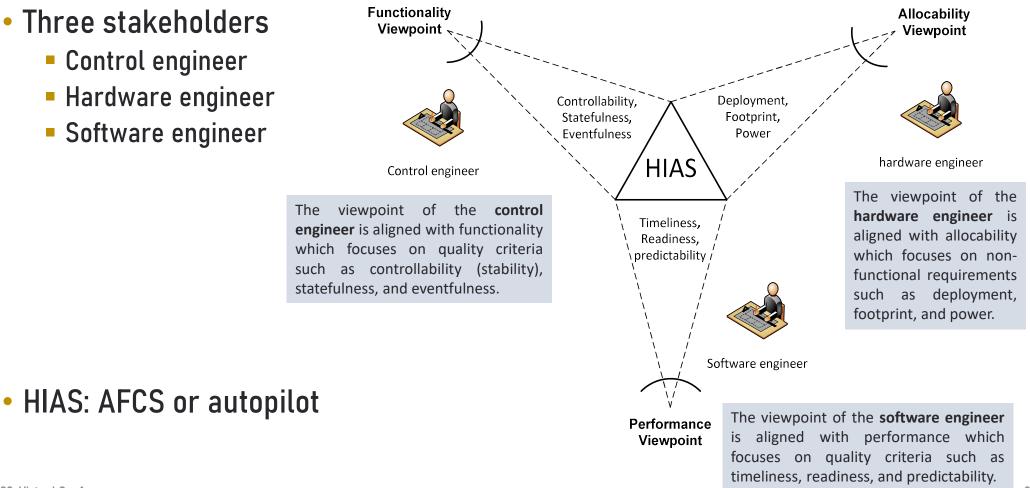


- Simple example but enough to show the idea
- Three disciplines
 - Control engineering
 - Hardware engineering
 - Software engineering
- Stakeholders from each discipline





- Three stakeholders
 - Control engineer
 - Hardware engineer
 - Software engineer



Simplified Example of Aircraft Autopilot



Changes on 1) SW-CW: Changes on data sources Laplace equation Control stability? U*(s) U(s) Latency \Rightarrow Stability R(s) E(s) Y(s) K(s+2) e^{-Ts} $(s + 1)(s^2 + 10s + 50)$ 2) CW-SW: Modelling \Rightarrow Footprint **Different control** strategy? 3 3) HW-CW: Input Different Architecture \Rightarrow Strategy sockets/ hardware connectors? footprint? 4) CW-HW: Airspeed Changes on Rudder sensors I Air data software effectors computer 2 execution? Q $Data \Rightarrow Socket$ Changes on Changes on the Pilot Control Pilot Displa Different network Pilot software end-totechnology Elevator Panel Panel software console end latency effectors footprint? 5) HW-SW: Network Attitude ٤ **Processing** \Rightarrow **Execution** Aileron 6 \$ sensors Air Data Servo Controller effectors FlightDirector -0-Autopilot Computer 6 Changes on 6) SW-HW: the software Position Attitude 8 code size Autopilot sensors Flight Heading compute Reference director System Servo Feedback Coding \Rightarrow Footprint computer Changes on software task processing Pilot display



Software Impact on Hardware and Control

Software Model Updates	Hardware Model Effects	Control Model Effects	
End to and latancy (OM)	SP: Execution SE: Task SC: Processing QF: Efficiency QC: Schedulability QM: Scheduling time	SP: Delay SE: Controller SC: Feedback control QF: Dependability QC: Responsiveness QM: Time response	
End-to-end latency (QM)	SP: Transmission SE: Packet SC: Communication QF: Efficiency QC: Responsiveness QM: Network latency		Computation
Code size (QM)	SP: Footprint SE: Memory SC: Computation QF: Efficiency QC: Allocability QM: Hardware use		Communicati
Data sizo (OM)	SP: Storage SE: Memory SC: Information QF: Efficiency QC: Mem Allocability QM: Mem use	SP: Control parameter SE: Controller SC: Feedback control QF: Dependability QC: Stability QM: Root Locus, Bode margins	SP: System Proper SE: System Elemen SC: System Capabi
Data size (QM)	SP: Bandwith SE: Network SC: Information QF: Efficiency QC: Network Usability QM: Network use	Givi. Noot Locus, boue margins	QF: Quality Factor QC: Quality Criteria QM: Quality Metri

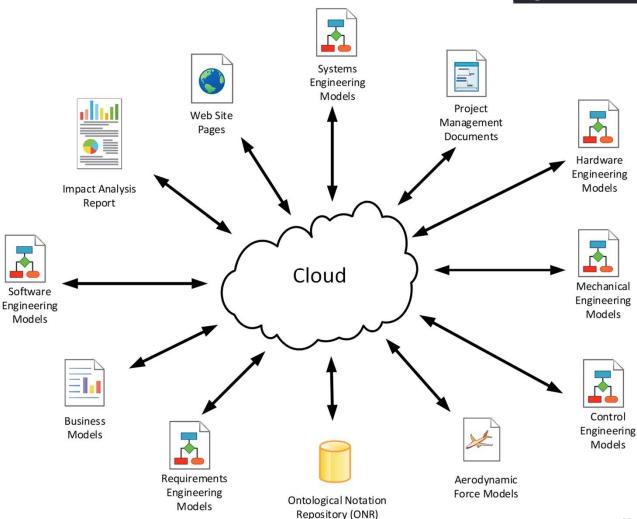


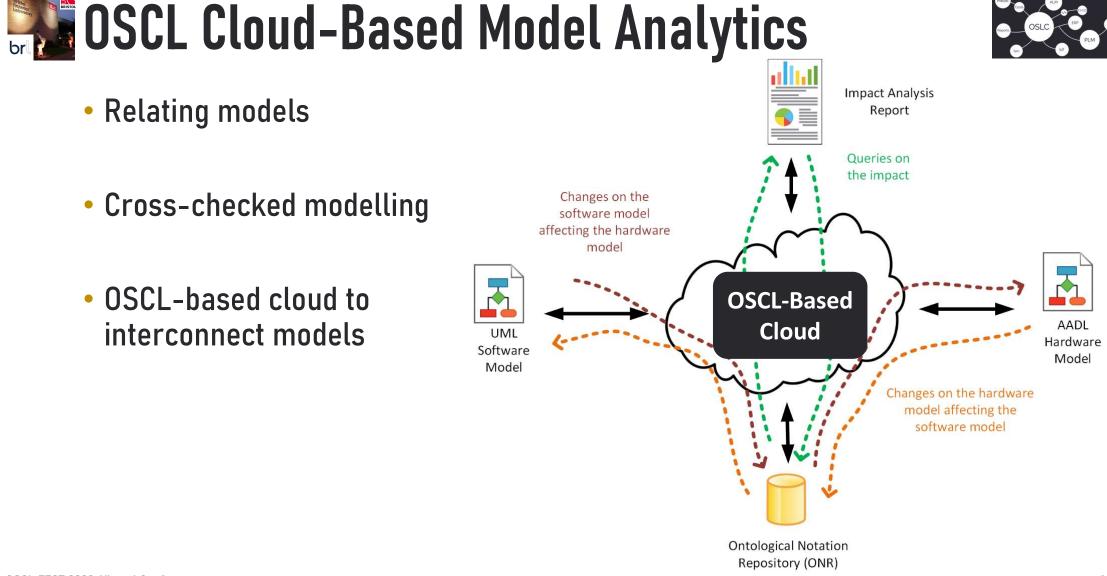
• HW-SW-HW Example Impact Analysis 5) HW-SW: Report **Processing** \Rightarrow **Execution** Changes on the software model 6) SW-HW: affecting the hardware model $Coding \Rightarrow Footprint$ UML AADL Notation Software Hardware Repository Model Model Changes on the hardware model affecting the software model 12





- Implementing a cloud-based approach for the framework
- Merging the model notation (parameters) into a single repository for analysis
- Modelling notation includes the functional and nonfunctional requirements and constraints from different engineering disciplines.









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AADL HW Ontologies make use of Hardware Diagram Footprint semantic diagrams to Engineering easily realize concepts hasCrossCheck the ontology and the Discipline Parameter connections between concepts. Software HW Consuption Thing hasImpact Model hasModel hasImpact Quality UML Diagram hasParamete SW SW nasCrossChe Performance Footprint



SoftwareFootprintParameter

UMLModel



- Protégé user interface for the ontology (ONR)
- Relating models and cross-checked modelling
- OSCL-based cloud to interconnect models

DL query:	DL query:	
Query (class expression)	Query (class expression)	
ControlEngineeringChangesImpactforSoftware or ControlCrossCheckedModellingforSoftware or CrossRelatedEquationParameter or ImpactonCoding	ControlEngineeringChangesImpactforHardware or ControlCrossCheckedModellingforHardware or CrossRelatedReferenceParameter or ImpactonIOConnecting	
Execute Add to ontology	Execute Add to ontology	
Query results	Query results	
Sultclasses (9 of 9)	Subclasses (9 of 9)	
😑 Coding	AADL_Diagram	
ControlCrossCheckedModellingforSoftware	ControlCrossCheckedModellingforHardware	
ControlEngineeringChangesImpactforSoftware	ControlEngineeringChangesImpactforHardware	
CrossRelatedEquationParameter	CrossRelatedReferenceParameter	
ImpactonCoding	😑 Hardware	
SWFootprint	IOConfiguration	
Software	ImpactonIOConnecting	
😑 UML_Diagram	Socket	
🔵 owl:Nothing	owl:Nothing	
instances (4 of 4)	instances (4 of 4)	
SoftwareCodeImpact	AADLModel	
SoftwareEngineeringDiscipline	HardwareEngineeringDiscipline	

HardwareSocketParameter IOConfigurationImpact



- Application scenario:
 - Software impacts on Hardware
- Software model on the Autonomous Model Analytics (AMA) application
- OSLC service interface for the software model
 - Creation of service
 - Resource shape
 - Query capability
 - Query resource

MBSE Costs	Alm grand	
Reports	OSLC ERP 3	D
Sm		

<oslc:s< th=""><th>service></th></oslc:s<>	service>
<oslc< th=""><th>::Service></th></oslc<>	::Service>
<0S	<pre>ilc:domain rdf:resource="http://open-services.net/ns/am#"/></pre>
<	coslc:creationFactory>
	<oslc:creationfactory></oslc:creationfactory>
	<pre><dcterms:tittle>Creation of Software Model Service</dcterms:tittle></pre>
	Creation of new resource (the software model)
	<pre><oslc:creation rdf:resource="http://host/creation/swmodelnotation"></oslc:creation></pre>
	Metadata of the XML resource
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<	<pre>/oslc:creationFactory></pre>
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	<oslc:querybase rdf:resource="http://host/query"></oslc:querybase>
	<pre></pre>



Software Model Resource Shape

<pre>?xml version="1.0" encoding="UTF-8"></pre>	-Resource shape for the software performance quality		
rdf:RDF xmlns:rdf="http://www.w3.org/1999/02/22-rdf-syntax-ns#"	<oslc:property></oslc:property>		
<pre>xmlns:dcterms="http://purl.org/dc/terms/"</pre>	<oslc:property></oslc:property>		
<pre>xmlns:foaf="http://xmlns.com/foaf/0.1/"</pre>	<pre><oslc:name>SWP</oslc:name></pre>		
<pre>xmlns:oslc="http://open-services.net/ns/core#"></pre>	<pre><dcterms:title>Software Performance</dcterms:title></pre>		
	<pre><oslc:propertydefinition rdf:resource="http://host/services/swm#SWP"></oslc:propertydefinition></pre>		
oslc:ResourceShape <pre>rdf:about="http://host/shapes/swnotationshape"></pre>	<pre><oslc:valuetype rdf:resource="http://www.w3.org/2001/XMLSchema#integer"></oslc:valuetype></pre>		
<pre><dcterms:title>Shape for the software model notation</dcterms:title></pre>	<pre><oslc:occurs rdf:resource="http://open-services.net/ns/core#Zero-or-one"></oslc:occurs></pre>		
<oslc:name>SWNotation</oslc:name> <oslc:describes rdf:resource="http://host/services/swm#Notation"></oslc:describes>	<pre><dcterms:description>Software performance based on hardware capacity</dcterms:description></pre>		
-Resource shape for the software footprint parameter			
<pre><oslc:property></oslc:property></pre>			
<oslc:property></oslc:property>			
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<pre><oslc:occurs rdf:resource="http://open-services.net/ns/core#Zero-or-one"></oslc:occurs></pre>			
<dcterms:description><mark>Use of hardware based on the software size</mark><td>scription></td></dcterms:description>	scription>		

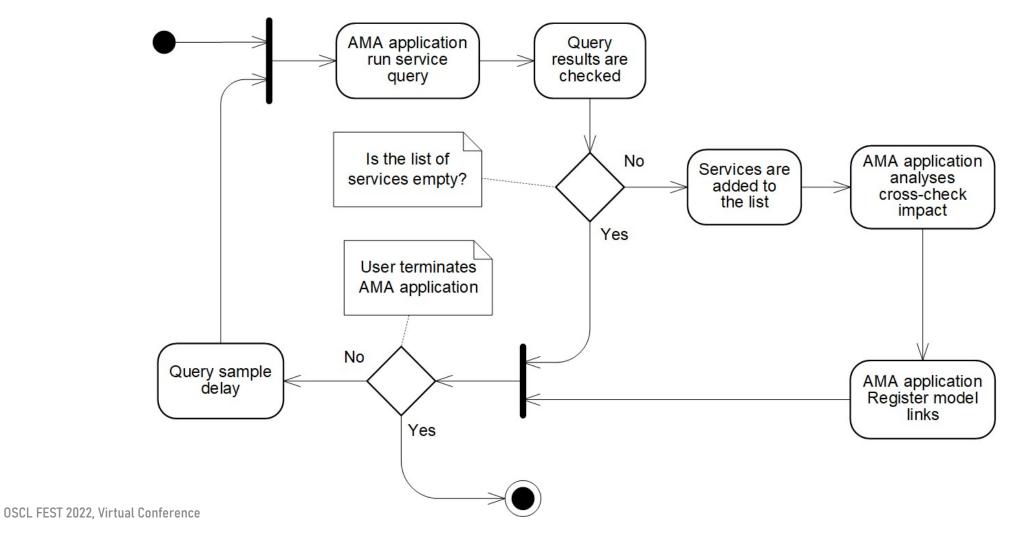


Software Model Query

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<pre>xmlns:dcterms="http://purl.org/dc/terms/"</pre>
<pre>xmlns:oslc="http://open-services.net/ns/core#"></pre>
<oslc:resourceshape rdf:about="http://host/shapes/swhwlinkqueryshape"></oslc:resourceshape>
<pre><dcterms:title>Shape for the software-hardware link</dcterms:title></pre>
<pre><oslc:type rdf:resource="http://open-services.net/ns/core#ResourceShape"></oslc:type></pre>
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<pre><oslc:describes rdf:resource="http://open-services.net/ns/swm#"></oslc:describes></pre>
-Resource shape for the software-hardware link query
<oslc:property></oslc:property>
<oslc:property></oslc:property>
<oslc:name>SWNotation</oslc:name>
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<pre><oslc:valueshape rdf:resource="http://host/shapes/swnotationshape"></oslc:valueshape></pre>
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<oslc:ismemberproperty>true</oslc:ismemberproperty>

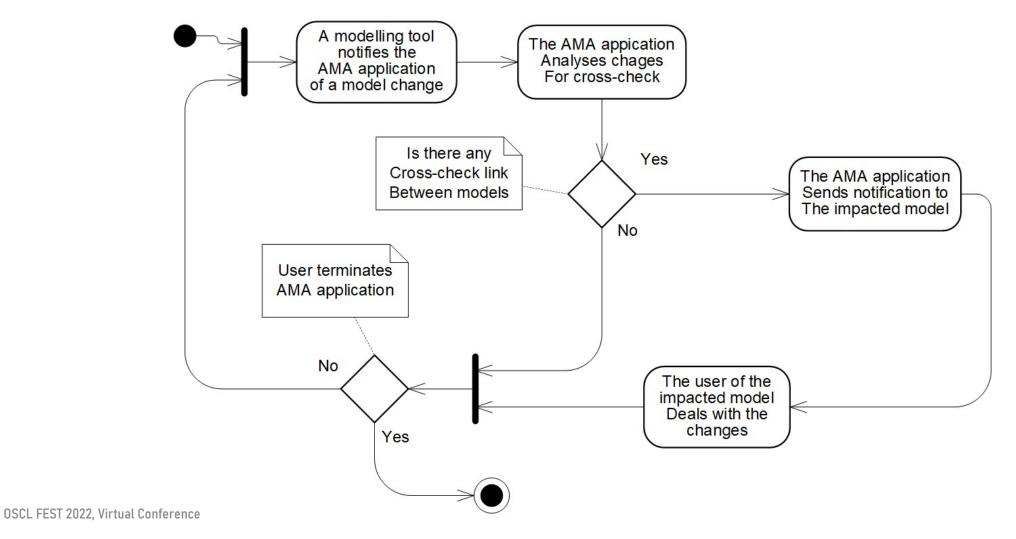


Discovery & Retrieve of Service Info





Analysis of Model Information







- Impacts from model updates on other models cannot necessarily to implement in real time
- Benefits from the model cross-checking framework but is complex by nature; toward process automation
- Model impacts can be also used for performance assessment
- OSCL is a good driver for the framework. However, it will add some complexity to the framework.
- OSCL facilities the model interconnections for cross-checking impact but a lot of work on producing the XML files
- Need for an automated process for the generation of OSLC interfaces for the framework
- <u>Future work</u>: development of framework prototype





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